

## Shenzhen Feite Model Co., Ltd.

## SHENZHEN FEETECH RC MODEL CO.,LTD. product

## specification PRODUCT SPECIFICATION

Customer (CUSTOMER)

model (MODEL) ÿSTS3215

Name (PRODUCT NAME): 7.4V 19KG.CM plastic shell metal tooth magnetic coding dual-axis TTL serial servo

EDITION ÿA/0

Before you place an order for this product, please read this specification and sign and return it in the confirmation box below.

Sign back before you place an order to purchase this product, please read this specification and in the following admit column.

ÿÿÿÿ/ FEETECH APPROVED

yyy/122120117(111012)					
write EDIT	review CHECKED	confirm APPROVED			
Li Yongchuan	Wu Gengyan	Feng Tanxin			

Customer confirmation/CUSTOMER APPROVED

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review	audit confirmatio	h
REVIEW	CHECKED	APPROVED
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Address: 2nd Floor, No. 60, Puxia Road, Liuyue, Henggang Town, Longgang District, Shenzhen City, Guangdong Province

ADD:Floor 2,No 60,PuXia Road,LiuYueHengGang Town, Long Gang District, ShenZhen,518173,China Tel/ Tel: 0755-89335266 Website/

Website: www.feetech.cn

Content  Environmental conditions  Test environment  Security Features and Authentication  Visual inspection  Electrical Characteristics  Mechanical properties	PRODUCTION PRODUCTION OF THE PROPULATION OF THE PRO	Product specification CT SPECIFICATION  collowing content CONTENT OF the specific product of the speci		2020	/Date: 0-04-10 umber Page:
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3	EEIECH	SHENZ MODEL CO.,LTD	THEN FEETECH RC		Version	EDITION:		
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М	Model/MODEL: Product specification STS3215 PRODUCT SPECIFICATION					/Date: 0-04-10		
					Page N	umber Page: 3/8		
1. Use e	Use environmental conditions Apply Environmental Condition:							
No.		Item (Item)		Specifica	ation			
1-1 Stor	age Temperature R	ange 1-2 Operating		-30ÿÿ80ÿ				
Temper	ature Range 2. Star	ndard Test Environment:		-20ÿÿ60ÿ				
No.		Item		Specifica	ation			
2-1 Temp	erature Range 2-2 Humi	idity		25ÿ ±5ÿ				
Range				65%±10%				
3. Secu	rity features and cer	tification Secure Performa	ance and Certificate					
No.	Project/Item	AuthenticationCertificate	Re	emarks				
3-1	ASTM F963	No	US toy testing standards EU					
3-2	EN71	No	market toy product norms and standards f	or electromagnetic				
3-3	FCC	No	interference in electronics and electrical a			frequency		
			range, to protect the normal operation of telecommunication networks and		storforongo wayoo			
3-4	electrical products. For any substance, it is not given unacceptable electromagnetic  EMC  Yes  and in the electromagnetic environment, it is also necessary to have the ability to m							
			machine,					
3-5	ROHS	Yes	device or system. The content of harmful substances in electronic and					
3-6	REACH NO electrical equipment. EU regulation "Registration, Evaluation, Authorization and Restriction of Chemicals"					iction of Chemicals"		
4. Appe	arance Inspection:							
No.	Iter	n	Spec	ification				
4-1 Appea	earance size OutlineDrawing		See the appendix for dimensions (it	em 12) See the appen	dix			
4-2	Appearance Appearance		No damage, not allowed to affect function  No damage and mustn't affect functions.					
5. Electi	rical Specification							
No.	Iter	n	Specification (Specification)	Specification (Spe	ecification) I	Remark Remark		
5-1 Typica	al operating voltage Ope	erating Voltage	6V	7.4V				
5-2 No Lo	ad Speed		0.238sec/60° (42RPM)	0.192sec/60 (52RPI				
5-3 Runni	ng Current (no load)		130mA	150m.	,			
			16.5kg.cm	19.5kg.c	m			
5-4 Sta	ll Torque (at locked)		229.54oz.in	271.28oz.i	in			
5-5	Stall current Stall Current (at locked)		2a	2.5A				
5-6 Idle C	e Current (at stopped)		6mA	6mA				
5-7 Worki	ng Voltage Input Voltage	9	4V-7	.4V				
5-8 Rated	Torgue		4kg.cm	5kg.cm	า			
5-9 Rated			500mA	650m <i>A</i>				
	r internal resistance Ter	minal resistance	2.5ÿ					
		mmai resisiane		-				
5-11 Kt C	11 Kt constant 8kg.cm/A							

7-10 Feedback Feedback

3	EEECH	RC	SHENZHEN FEETECH RC MODEL CO.,LTD.			Version EDITION: A/0	
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		.1					Page Number Page: 4/8
	hanical Specifica	ation:					
No.	Item		Specific	cation		Rem	arks
	arance Size 6-2		45.2X24.7X35			See drawings See	e drawings
	e No limit 6-3 Case mate		material PA+GF				
	opper 6-5 Bearing type B	all	PA+GF			1	
bearings							
			ТуреТуре	12Bits Magr	netic		
6-6 Angle	Sensor Angle Sansor		Angle Angle 36	0°			
			Lifespan Life No	limit			
			TypeType 5264	-3P		接口定义	117 18
	M		Material material	PP		G — 1 V — 2 S — 3	*
6-7 Connectors and Cables Connector and Cable	line length		15CM				
		Length	1	GND	20.9	2.5+8.05	
		pin definition	pin definition Pin	2	Vcc	*	<b>+++</b>
			Definition	3 Signal/TT		P. 0	C. B LAYOUT
6-8 The V	Veight 6-9 Output		55±1g				
shaft Hor	Type 6-10 Gear Ratio		25T/OD5.9mm				
6-11 Bacl	Lash Rocker arm		1/345				
dummy			ÿ0.5°				
6-12	The rocker phantom		0°				_
6-13	output shaft screw The rocker screw		M3X6				
6-14 Moto	r Motor		Core Motor				
7-1 Cd	ontrol Specification	on: Item					
No.				Specification		Remarks	
7-1 Comr	nand Signal			Digital Packet			
7-2 Proto	rotocol Type Protocol Type		Half Duplex Asynchronous Serial Communication		8bit, 1stop, No Parity		
7-3 ID rar	rar ge ID range		0-253		Customizable		
	mmunication Baud Rate		38400bps 1 Mbps		Customizable (factory defaul 1Mbps)		
7-5 Contr	ontrol Algorithm		PID			Customizable (support modification)	
	n Neutral Position			180°ÿ2048ÿ			
	on angle Running degree			360°(when 0ÿ4096)			
7-8 Electi	onic resolution Resolution	n [deg/pulse]		0.088°(360°/4096)			
7-9 Rotat	ng Direction			Clockwise(0	ÿ4096ÿ		Customizable

Load (load), Position (position), Speed (working speed), Input

Voltage (input voltage), Current (operating current), Temperature (operating temperature)

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7-2. Cor	ntrol Specification:			Т	
No.	Ite	m	Specification	Remarks (remarks) It enters the	
	7-11 Electronic Protection		Overload Over Load	protection after being blocked at more than 80% of the locked rotor and lasts for 2s. Re- issue the position command and the overload protection flag will be cleared. The percentage and duration of the locked rotor can be customized.	
7-11 E			Over Current	and set. The running current is greater than 2A and lasts for 2s After that, turn off the output and enter the over-current protection, re-send the position command, the over-current protection flag will be cleared, the current value and duration can	
		Over Voltage	to be greater than 7.4V or less than 4V to enter the protection, and the protection will be automatically released after the voltage returns to the normal range, the voltage value range can be cu		
			Overheating Over Hot	Turn off the tongue output when the temperature is higher than 70°C	
			Mode 0: Angle Servo Mode	Default this mode, 0-360 degree absolute position controllable	
			Mode 1: Speed closed-loop motor mode	In motor mode, as the load increases, the speed is intelligently maintained without deceleration.	
7-12 Operating Modes		Mode 2: Speed open loop motor mode	Motor mode, as the load increases, the speed will continue to slow down		
			Mode 3: Step mode	Step movement relative to the current position	
7-13 Mu	Multi-Loop Mode		Under the highest precision, it can control the absolute position of plus	Expand the resolution and double the number of turns	
7-14 Ce	ntering function Step	Middle Position	or minus 7 turns, but the number of turns will not be saved when the power is off.	Enter 128 for address 40	

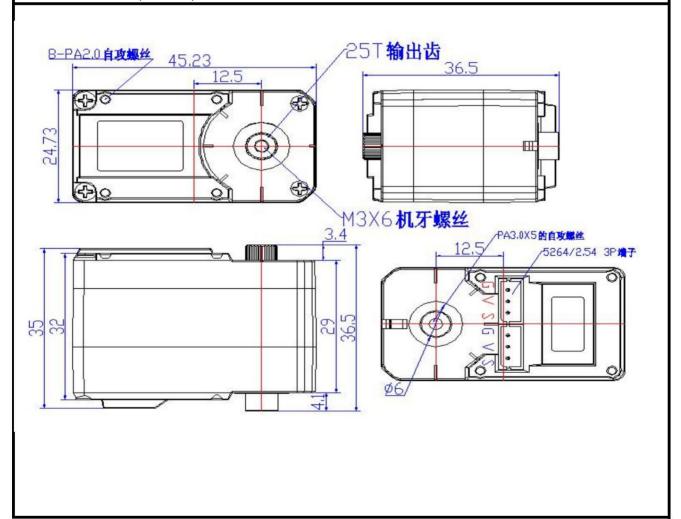
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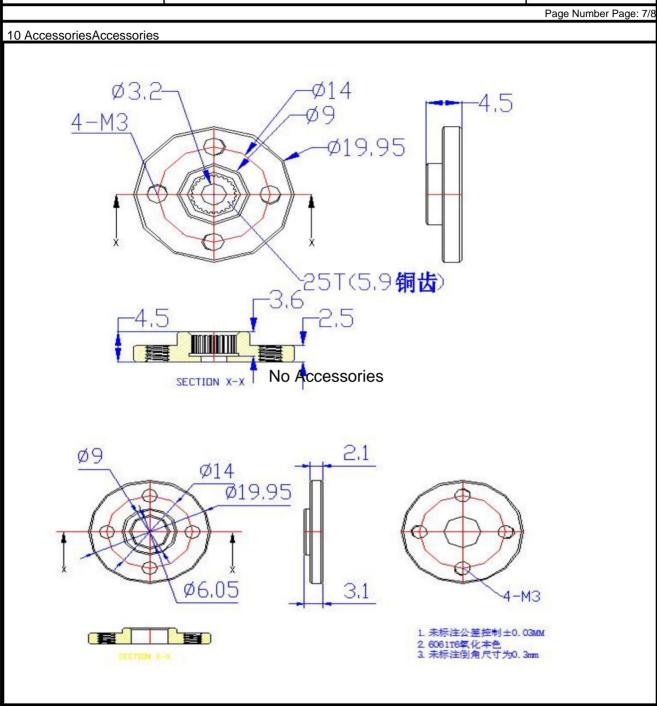
8 Reliability	<sup>'</sup> Testing	Reliability	/ Testing
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No.	Item	(Specification)	Remarks
8-1 Load	life test Life test	>100000 times	Forward rotation 60 degrees 0.25S, stop 0.5S, reverse 60 degrees 0.25S, stop 0.5S for one time, continuous cycle work, load 1/5 stall torque.
8-2 The r	notor noises 45±5dB		Ambient noise 40-45 dB Tested at a distance of 30cm from the noise meter
8-3	Steering gear noises	60±5dB	Ambient noise 40-45 dB Tested at a distance of 30cm from the noise meter
8-4	Waterproof performanceWaterproof performance	No	

## 9 Outside Dimension (Unit: mm)



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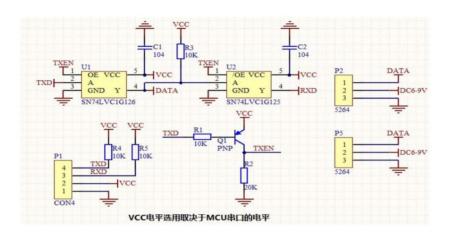
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11 Interface definition Interface Definition Control

signal parameter (Control signal parameter)

Maximum position update rate Max Position Update	1 ms	
Rate Signal high level voltage Signal high	2V-5V	
Voltage Signal low level voltage Signal Low Voltage	0.0V-0.45V	



12 The Packaging Detail/Product List

