

W5100S-EVB-Pico Getting Started Guide for AWS IoT Core

Version 1.0.0



http://www.wiznet.io/

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1 Document Information

1.1 Revision History (Version, Date, Description of change)

| Version | Date | Description of change |
|---------|------------|-----------------------|
| V1.0.0 | 2021-11-25 | Initial Release |

2 Overview

The W5100S-EVB-Pico is a microcontroller evaluation board based on the Raspberry Pi RP2040 microcontroller chip and full hardwired TCP/IP controller W5100S chip. The W5100S-EVB-Pico has the same role as the Raspberry Pi Pico platform and includes W5100S, so the Ethernet function is basically included.

- Raspberry Pi Pico Clone
- Ethernet (W5100S Hardwired TCP/IP CHIP)

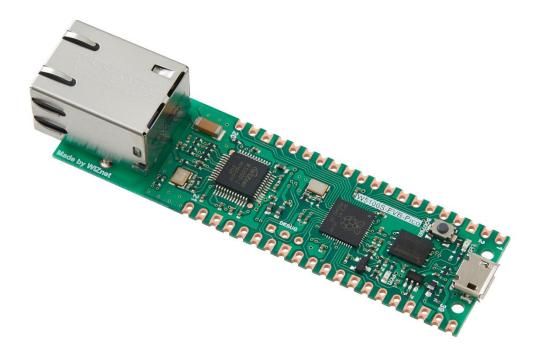


Figure 1. W5100S-EVB-Pico



3 Hardware Description

3.1 DataSheet

https://docs.wiznet.io/assets/images/w5100S-evb_pico_schematic-52444497b86d1ef0550d99aba4c0c164.png

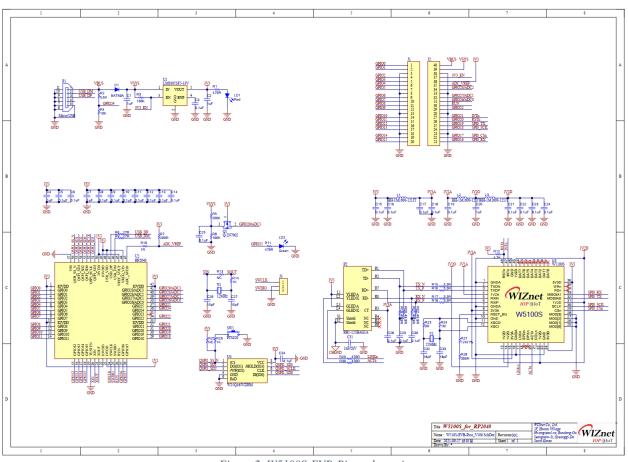


Figure 2. W5100S-EVB-Pico schematic

3.2 Standard Kit Contents

- W5100S-EVB-Pico : 1EA
- 1 x 20 2.54mm pitch pin header : 2EA



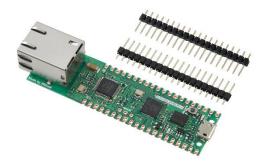


Figure 3. W5100S-EVB-Pico package

3.3 User Provided items

•

USB type A to USB micro B cable



Figure 4. USB type A to USB micro B cable

- Ethernet cable
- Desktop or laptop

3.4 3rd Party purchasable items

None

3.5 Additional Hardware References



https://docs.wiznet.io/Product/iEthernet/W5100S/w5100s-evb-pico

4 Set up your Development Environment

4.1 Tools Installation (IDEs, Toolchains, SDKs)

Windows 10 was used during preparation of this guide document. Linux and MacOS user should use compatible software, hardware-wise there is no difference. Please refer to the guide in section 4.4 to find instructions for installing toolchain on Linux and MacOS.

1) Install the Toolchain

To build you will need to install extra tools below.

- <u>ARM GCC compiler</u>
- <u>CMake</u>
- Build Tools for Visual Studio
- Python 3.9
- <u>Git</u>
- Visual Studio Code

Download the executable installer for each of these from the links above, and then carefully follow the instructions in the following sections to install all six packages on to your Windows computer.

1 Install ARM GCC compiler



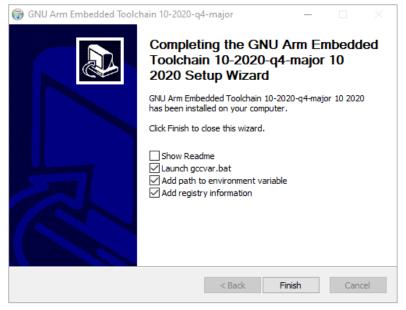


Figure 5. Install ARM GCC compiler

During installation you should check the box to register the path to the ARM compiler as an environment variable in the Windows shell when prompted to do so.

2 Install CMake

| 记 Install Options | _ | | \times |
|-----------------------------------------------------------------|---|-----|----------|
| Install Options | | | |
| Choose options for installing CMake 3.20.2 | | | |
| By default CMake does not add its directory to the system PATH. | | | |
| O Do not add CMake to the system PATH | | | |
| Add CMake to the system PATH for all users | | | |
| \bigcirc Add CMake to the system PATH for the current user | | | |
| Create CMake Desktop Icon | | | |
| | | | |
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Figure 6. Install CMake

During the installation add CMake to the system <u>PATH</u> for all users when prompted by the installer.



(3) Install Build Tools for Visual Studio

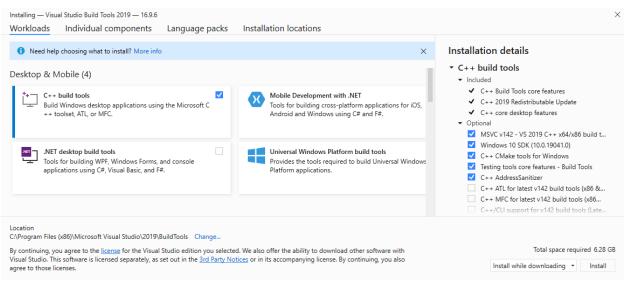


Figure 7. Install Build Tools for Visual Studio

When prompted by the Build Tools for Visual Studio installer you need to install the C++ build tools only.

④ Install Python 3.9

During the installation, ensure that it's installed 'for all users' and add Python 3.9 to the system <u>PATH</u> when prompted by the installer. You should additionally disable the <u>MAX_PATH</u> length limit when prompted at the end of the Python installation.



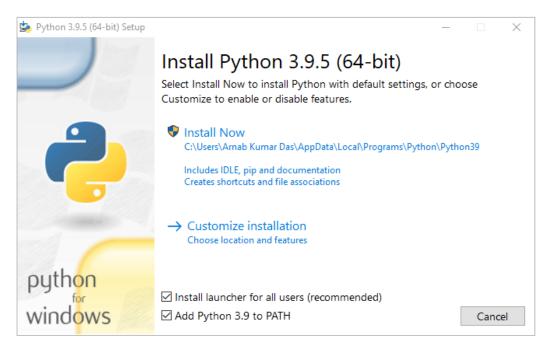


Figure 8. Install Python

(5) Install Git

When installing Git you should ensure that you change the default editor away from vim.

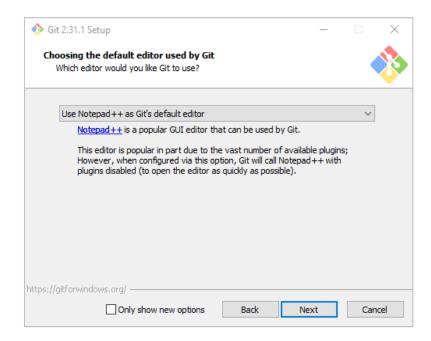


Figure 9. Install Git

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6 Install Visual Studio Code

During the installation add Visual Studio Code to the system PATH.

| 🗙 Setup - Microsoft Visual Studio Code (User) - | | \times |
|----------------------------------------------------------------------------------------------------------------|---------|----------|
| Select Additional Tasks | | |
| Which additional tasks should be performed? | | |
| Select the additional tasks you would like Setup to perform while installing Visual Studio Code, then Next. | ı click | |
| Additional icons: | | |
| Create a desktop icon | | |
| Other: | | |
| Add "Open with Code" action to Windows Explorer file context menu | | |
| Add "Open with Code" action to Windows Explorer directory context menu | | |
| Register Code as an editor for supported file types | | |
| Add to PATH (requires shell restart) | | |
| | | |
| | | |
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| | | |
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Figure 10. Install Visual Studio Code

2) Clone the Raspberry Pi Pico SDK and WIZnet example repository using below commands

- SDK : https://github.com/raspberrypi/pico-sdk
- Example : <u>https://github.com/Wiznet/RP2040-HAT-AWS-C</u>

// create a project directory
D:\>mkdir RP2040
D:\>cd RP2040
// get the SDK
D:\RP2040> git clone -b master https://github.com/raspberrypi/pico-sdk.git
D:\RP2040> cd pico-sdk
D:\RP2040\pico-sdk> git submodule update --init
// get the example
D:\RP2040\pico-sdk> cd ..





3) Set up Visual Studio Code

- ① Open a new Visual Studio 2019 Developer Command Prompt
- 2 Run the below command to open Visual Studio Code

D:> code



- (3) Opening Visual Studio Code from Developer Command Prompt
- (4) Open Extensions

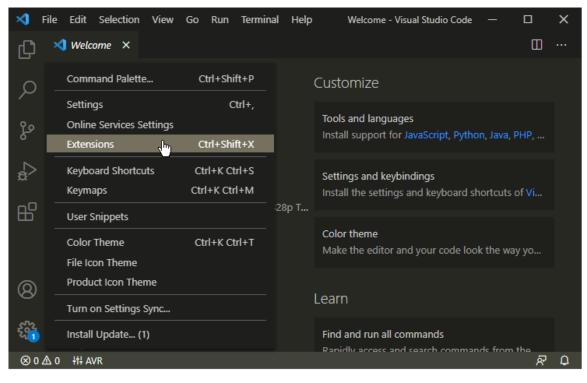


Figure 12. Install Extensions in Visual Studio Code

- (5) Install some tools
 - CMake Tools
 - C/C++
- 6 Open CMake Tools Extension Settings
- ⑦ Scroll down and set up some items
 - Add Cmake: Configure Environment Item as <u>PICO_SDK_PATH</u>
 - Add Cmake: Configure Environment Value as <u>D:\RP2040\pico-sdk</u>
 - Add Cmake: Generator as <u>NMake Makefiles</u>



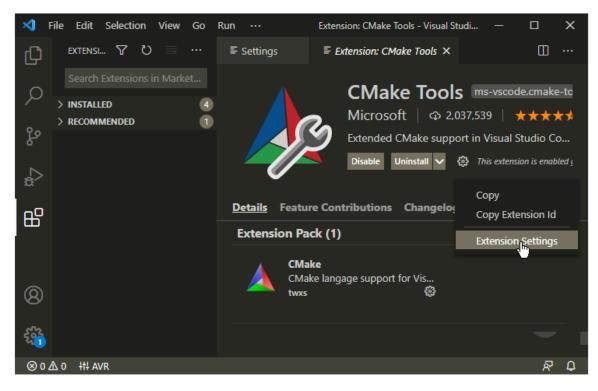


Figure 13. CMake Tools Extension Settings in Visual Studio Code

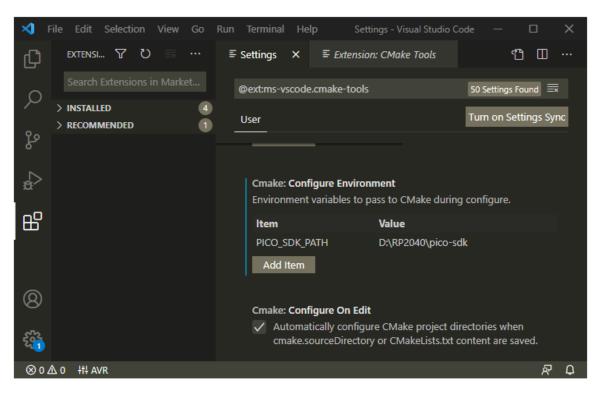


Figure 14. Add CMake Configure Environment path

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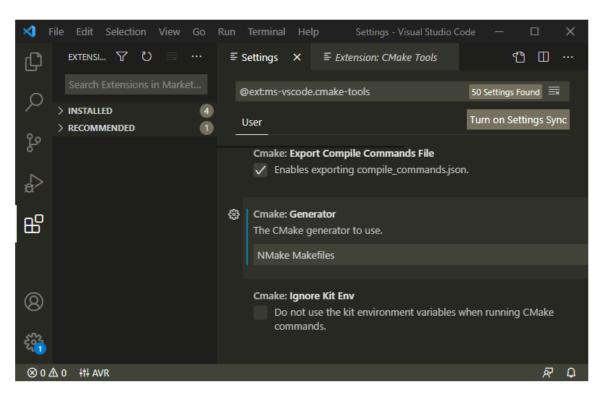


Figure 15. Add CMake Generator name

- (8) Add folder <u>RP2040-HAT-AWS-C</u> to Visual Studio Code
- (9) Visual Studio Code will scan for kits
- Delect 'Yes' when asked: Would you like to configure project RP2040-HAT-AWS-C?
- (1) Select 'Yes' if you like to configure the project upon opening
- Dick CMake in the bottom bar to select the kit RP2040-HAT-AWS-C
- (13) Select Debug / Release based on your preference
- (4) Visual Studio Code will save all file and configure the project
- (5) Click on Build to build all examples, if no error Build will finish with exit code 0

4.2 Other software required to develop and debug applications for the device

Serial terminal program is required for operation check and debugging.

<u>Tera Term</u>

You may use your preferred serial terminal program.



4.3 Other pre-requisites

None

4.4 Additional Software References

Refer to the '9.2. Building on MS Windows' section of 'Getting started with Raspberry Pi Pico' document below to set up the development environment.

• Getting started with Raspberry Pi Pico

And refer to the links below for instructions how to setup environment and proceed with tests.

- <u>Getting Started with AWS IoT SDK Examples</u>
- <u>Connect AWS IoT through MQTT</u>
- 5 Set up your hardware



Figure 16. W5100S-EVB-Pico front



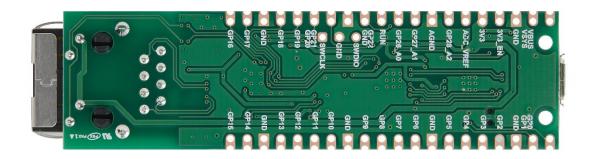


Figure 17. W5100S-EVB-Pico back

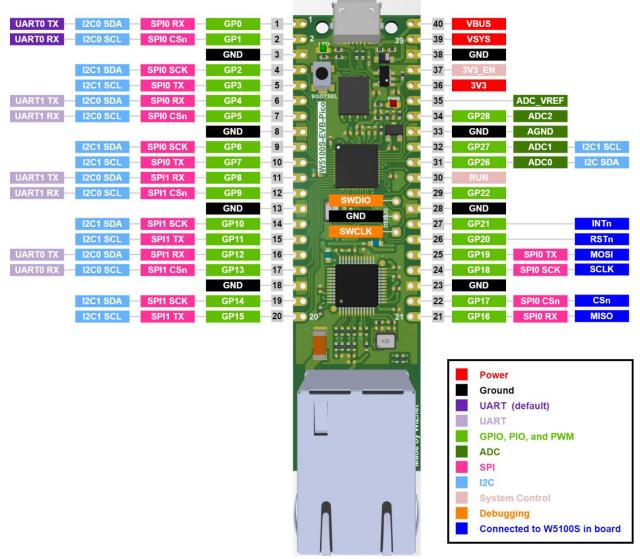


Figure 18. W5100S-EVB-pico pin-out

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W5100S-EVB-Pico pin-out is directly connected to the GPIO of RP2040 as shown in the picture above. It has the same pinout as the Raspberry Pi Pico board. However, GPIO16, GPIO17, GPIO18, GPIO19, GPIO20, GPIO21 are connected to W5100S inside the board. These pins enable SPI communication with W5100S to use Ethernet function. If you are using the Ethernet function, these pins cannot be used for any other purpose.

| I/O | Pin name | Description |
|-----|----------|------------------------------------------------|
| Ι | GPIO16 | Connected to MISO on W5100S |
| 0 | GPIO17 | Connected to CSn on W5100S |
| 0 | GPIO18 | Connected to SCLK on W5100S |
| 0 | GPIO19 | Connected to MOSI on W5100S |
| 0 | GPIO20 | Connected to RSTn on W5100S |
| Ι | GPIO21 | Connected to INTn on W5100S |
| Ι | GPIO24 | VBUS sense - high if VBUS is present, else low |
| 0 | GPIO25 | Connected to user LED |
| Ι | GPIO29 | Used in ADC mode (ADC3) to measure VSYS/3 |

The RP2040 GPIO used inside W5100S-EVB-Pico is as follows.

Apart from GPIO and ground pins, there are 7 other pins on the main 40-pin interface.

| Pin no. | Pin name | Description |
|---------|----------|------------------------------------------------------------------------------------------------------------------------------------|
| PIN40 | VBUS | Micro-USB input voltage, connected to micro-USB port pin 1. Nominally 5V. |
| PIN39 | VSYS | Main system input voltage, which can vary in the allowed range 4.3V to 5.5V, and is used by the on-board LDO to generate the 3.3V. |
| PIN37 | 3V3_EN | Connects to the on-board LDO enable pin. To disable the 3.3V (which also de-powers the RP2040 and W5100S), short this pin low. |
| PIN36 | 3V3 | Main 3.3V supply to RP2040 and W5100S, generated by the on-board LDO. |
| PIN35 | ADC_VREF | ADC power supply (and reference) voltage, and is generated on W5100S- EVB-Pici by filtering the 3.3V supply. |
| PIN33 | AGND | Ground reference for GPIO26-29. |
| PIN30 | RUN | RP2040 enable pin, To reset RP2040, short this pin low. |

6 Setup your AWS account and Permissions

Refer to the instructions at <u>Set up your AWS Account</u>. Follow the steps outlined in these sections to create your account and a user and get started:

- Sign up for an AWS account and
- Create a user and grant permissions.
- Open the AWS IoT console

Pay special attention to the Notes.



7 Create Resources in AWS IoT

Refer to the instructions at <u>Create AWS IoT Resources</u>. Follow the steps outlined in these sections to provision resources for your device:

- Create an AWS IoT Policy
- Create a thing object

Pay special attention to the Notes.

8 Provision the Device with credentials

You need to enter the root certificate, client certificate and private key that were downloaded earlier.

Root certificate uses the RSA 2048 bit key, Amazon Root CA 1, and does not use the public key.

Device certificate and key can be set in 'mqtt_certificate.h' in 'RP2040-HAT-AWS-C/Interface/' directory.

```
uint8_t mqtt_root_ca[] =
"-----BEGIN CERTIFICATE-----\r\n"
"...\r\n"
"-----END CERTIFICATE-----\r\n";
uint8_t mqtt_client_cert[] =
"-----BEGIN CERTIFICATE-----\r\n"
"...\r\n"
"-----END CERTIFICATE-----\r\n";
uint8_t mqtt_private_key[] =
"-----BEGIN RSA PRIVATE KEY-----\r\n";
"...\r\n"
```



| ×1 <u>F</u> | ile <u>E</u> dit <u>S</u> election <u>V</u> iew <u>G</u> o <u>R</u> un <u>T</u> erminal <u>H</u> | lp mqtt_certificate.h - RP2040-HAT-AWS-C - Visual Studio Code |
|-------------|--------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------|
| ф | EXPLORER ···· | C mqtt_certificate.h M × |
| | ✓ RP2040-HAT-AWS-C | Interface > C mqtt_certificate.h > Ø mqtt_private_key |
| ρ | > build • | |
| \sim | > examples • | 2 * Copyright (c) 2021 WIZnet Co.,Ltd |
| 90 | ✓ Interface ● | |
| Ро 2К+ | M CMakeLists.txt M | 4 * SPDX-License-Identifier: BSD-3-Clause 5 */ |
| | C core_http_config.h M | |
| æ | C core_mqtt_config.h M | 7 #ifndef _MQTT_CERTIFICATE_H_ |
| | C dns_config.h M | 8 #define _MQTT_CERTIFICATE_H_ |
| B | C dns_interface.c M | 9 |
| | C dns_interface.h M | <pre>10 uint8_t mqtt_root_ca[] = 11 "BEGIN CERTIFICATE\r\n"</pre> |
| | C http_certificate.h M | <pre>11BeGIW CERTIFICATE(NU 12 "MIIDQTCCAimgAwIBAgITBmyfz5m/jAo54vB4ikPmljZbyjANBgkqhkiG9w0BAQsF\r\n"</pre> |
| | C http_transport_interface.c M | 13 "ADA5MQswCQYDVQQGEwJVUzEPMA0GA1UEChMGQW1hem9uMRkwFwYDVQQDExBBbWF6\r\n" |
| | C http_transport_interface.h M | 14 "\r\n" |
| | C mqtt_certificate.h M | 15 "5MsI+yMRQ+hDKXJioaldXgjUkK642M4UwtBV8ob2xJNDd2ZhwLnoQdeXeGADbkpy\r\n" |
| | C mqtt_transport_interface.c M | 16 rqXRfboQnoZsG4q5WTP468SQvvG5\r\n" |
| | C mqtt_transport_interface.h M | 17 "END CERTIFICATE\r\n"; |
| | C ssl_config.h M | 18 19 uint8 t mqtt client cert[] = |
| | C ssl_transport_interface.c M | 20 "BEGIN CERTIFICATE\r\n" |
| | C ssl_transport_interface.h M | 21 "MIIDWjCCAkKgAwIBAgIVAPLU2Xit5g+lAs/rcT0aTlwJEbgSMA0GCSqGSIb3DQEB\r\n" |
| | C timer_interface.c M | 22 CwUAME0xSzBJBgNVBAsMQkFtYXpvbiBXZWIgU2VydmljZXMgTz1BbWF6b24uY29t\r\n" |
| | C timer_interface.h M | 23 "\r\n" |
| | C util.c M | 24 "g0cU62CJ4bhWVkWlW3ok2KqT/wCCFt409QMMhjtCWHv0ZyDgdaT968uUjxZ74AY9\n\n" |
| | C util.h M | <pre>25 "+g61xqbSfFTpl8eTB4V2s1C8DghPnIYJtyPw1Vz900sIOko8SGcQTNBA65GKnQ==\r\n" 26 "END CERTIFICATE\r\n";</pre> |
| | > libraries • | 27 |
| | > patches • | <pre>28 uint8_t mqtt_private_key[] =</pre> |
| | > static • | 29 "BEGIN RSA PRIVATE KEY\n" |
| | ♦ .gitmodules | 30 "MIIEowIBAAKCAQEArX1FRK5WhaOhUCT+EqJhCIEDTNqdoyajpwMZ+k3V4gRUPp7y\r\n" |
| | M CMakeLists.txt M | 31 "exGH6JmJjZ1N0TfA+VqfHXzh9/wIyr00iD2c3FnIbduzpUmqkNAP/grAdb2JAqpk\r\n" 32 "\r\n" |
| | getting_started.md | 32\r\n 33 "/hJ28EJZN4Cfe+JhK6VehU2bJDCRYHUM171MyenfB3r6RDHPZ/t4dJVjp/j/3MPU\r\n" |
| | ■ pico_sdk_import.cmake M | 34 "Cp9MdASnXqC3yL3pScz88C7ELxLmgh0x9mFnZdAuEpEtIxthe4cA\r\n" |
| | README.md M | 35 "END RSA PRIVATE KEY\r\n"; |
| | ■ rp2040_hat_aws_c-patch.cmake M | |
| | | 37 #endif /* _MQTT_CERTIFICATE_H_ */ |
| | | 38 |
| | | |
| | | |
| | | |
| | | |

Figure 19. Set up certificates

9 Build the demo

- ① Click 'build' in the status bar at the bottom of Visual Studio Code or press the 'F7' button on the keyboard to build.
- ② When the build is completed, 'aws_iot_mqtt.uf2' is generated in 'RP2040-HAT-AWS-C/build/examples/aws_iot_mqtt/' directory.

10 Run the demo

① While pressing the BOOTSEL button of Raspberry Pi Pico or W5100S-EVB-Pico power on the board, the USB mass storage 'RPI-RP2' is automatically mounted.



| 💻 🛃 🔚 🖛 This PC | | | | — C | |
|------------------------------|--------------------------------------------------------------|---------------------------------|--------------------|----------------|-------------------|
| File Computer V | liew | | | | ^ ? |
| Properties Open Rename | Access Map network Add a network media v drive v location | Open Settings ₪ Manage | | | |
| Location | Network | System | | | |
| ← → · ↑ | nis PC | | ې ټ | Search This PC | |
| 3D Objects | Desktop | Docu | uments | | ^ |
| Downloads | Music | Pictu | ires | | |
| Videos | | | | | |
| \sim Devices and drives (4 | 4) | | | | |
| Local Disk (C:) | Data (D |) 시스 | 템 예약 (E:) | | |
| 105 GB free of 23 | 31 GB 811 GB | free of 931 GB 84.9 1 | MB free of 99.9 MB | | |
| RPI-RP2 (F:) | | | | | |
| 127 MB free of 1 | 27 MB | | | | |
| 11 items | | | | | |
| | Figure 20 Autor | natically mounted USB mass stor | rage 'RPI-RP2' | | <u>u</u> <u> </u> |
| | 1.8000 20.11000 | anothing monned OBD mass stor | | | |

- ② Drag and drop 'aws_iot_mqtt.uf2' onto the USB mass storage device 'RPI-RP2'.
- ③ Connect to the serial COM port of Raspberry Pi Pico or W5100S-EVB-Pico with Tera Term.

| M | Tera Term - [c | lisconnecte | ed] VT | | | | | | | _ | \times |
|------|----------------|-------------|--------|------|--------------------|----------------|-----------------------------|-------------------|--------|---|--------------|
| File | Edit Setup | Control | Window | Help | | | | | | | |
| | | | | | Tera Term: New con | nection | | | × | | ^ |
| | | | | | ⊖ TCP/ <u>I</u> P | Hos <u>t</u> : | myhost.exam | ple.com | ~ | | |
| | | | | | | Service: | ✓ Hist <u>o</u> ry ○ Telnet | TCP port#: 22 | | | |
| | | | | | | | | SSH version: SSH2 | \sim | | |
| | | | | | | | ○ Other | IP version: AUTO | \sim | | |
| | | | | | ● S <u>e</u> rial | Po <u>r</u> t: | COM9: USB | 직렬 장치(COM9) | ~ | | |
| | | | | | [| OK | Cancel | <u>H</u> elp | | | |
| | | | | | | | | | | | |
| | | | | | | | | | | | |
| | | | | | | | | | | | |
| | | | | | | | | | | | \checkmark |

Figure 21. Connect to the serial COM port of W5100S-EVB-Pico



- ④ When connecting to the serial COM port of W5100S-EVB-Pico, use following settings to set up the serial port.
 - Baud rate : 115,200
 - Data bit : 8
 - Parity bit : none
 - Stop bit : 1
 - Flow control : none

| VT | CON | 9 - Tera | Term VT | | | | | | | | _ | \times |
|------|-----|----------|---------|--------|------|----------------------------------------------------------------------------------------------------------------------------|----------------------------------------------------------|-------------------------|---------------------|----------|---|----------|
| File | Edi | Setup | Control | Window | Help | | | | | | | |
| | | | | | | Tera Term: Serial port | setup and conne | ection | | \times | | ^ |
| | | | | | | <u>P</u> ort: Sp <u>e</u> ed: | COM9 ~ | | <u>N</u> ew setting | | | |
| | | | | | | <u>D</u> ata: | 8 bit 🗸 🗸 | | Cancel | | | |
| | | | | | | P <u>a</u> rity: | none ~ | | | | | |
| | | | | | | <u>S</u> top bits: | 1 bit 🗸 | | <u>H</u> elp | | | |
| | | | | | | Elow control: | none ~ | | | | | |
| | | | | | | Transm 0 | iit delay msec/ <u>c</u> har | 0 msec | /line | | | |
| | | | | | | Device Friendly N Device Instance II Device Manufacti Provider Name: N Driver Date: 6-21 Driver Version: 10 | D: USB₩VID_2E8. urer: Microsoft 1icrosoft -2006 | 상치(COM9) A&PID_000A8 | kMI_00₩8&280 | ~ | | |
| | | | | | | < | | | > | | | |
| | | | | | | | | | | | | |
| | | | | | | | | | | | | ~ |

Figure 22. Set up serial port

- 5 Reset your board.
- (6) If the Connect AWS IoT through MQTT example works normally on W5100S-EVB-Pico, you can see the network information of W5100S-EVB-Pico, connecting to the AWS IoT and publishing the message.



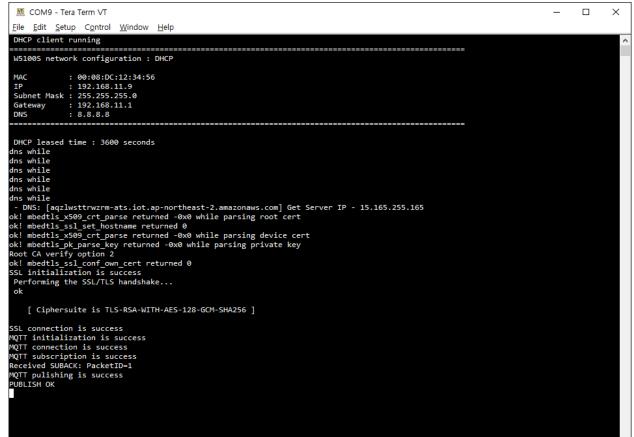


Figure 23. Publish the message from W5100S-EVB-Pico

| aws Services ▼ | Q Search 1 | or services, features, blogs, docs, and more [Alt+S] | ل Glung Kim ▼ Secul ▼ Support ▼ | | | | | | | | | |
|---------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------|---------------------------------------------------------------------------|--|--|--|--|--|--|--|--|--|
| AWS IoT \times | AWS IoT > MQTT test client | | | | | | | | | | | |
| Monitor Activity | MQTT test client tern You can use the MQTT test client to monitor the MQTT messages being passed in your AWS account. Devices publish MQTT messages that are identified by topics to communicate their state to AWS IoT. AWS IoT also publishes MQTT message inform devices and apps of changes and events. You can subscribe to MQTT message topics and publish MQTT messages topics by using the MQTT test client. | | | | | | | | | | | |
| ▶ Connect | | | | | | | | | | | | |
| Manage Fleet Hub | Subscribe to a topic Publish to a topic | Subscribe to a topic Publish to a topic | | | | | | | | | | |
| Greengrass | Topic filter Info The topic filter describes the topic(s) to which you want to subscribe. | The topic filter can include MQTT wildcard characters. | | | | | | | | | | |
| Secure | \$aws/things/my_rp2040_thing/shadow/update | | | | | | | | | | | |
| Defend | Additional configuration | | | | | | | | | | | |
| ▶ Act Test | Subscribe | | | | | | | | | | | |
| Software | Subscriptions | \$aws/things/my_rp2040_thing/shadow/update | Pause Clear Export Edit | | | | | | | | | |
| Settings Learn Feature spotlight | \$aws/things/my_rp2040_thing/shadow/update 🌣 🗙 | Saws/things/my_rp2040_thing/shadow/update | November 17, 2021, 16:45:14 (UTC+0900) | | | | | | | | | |
| Documentation 2 New console experience Tell us what you think | | { "message": "Hello, World!", "publish count": "@" } | | | | | | | | | | |
| | | | | | | | | | | | | |
| | | | | | | | | | | | | |
| | | | | | | | | | | | | |
| | | | | | | | | | | | | |
| Feedback English (US) 🔻 | | © 2008 - 2021, Amazon Web Services, Inc. or its affilia | ates. All rights reserved. Privacy Policy Terms of Use Cookie preferences | | | | | | | | | |

Figure 24. Receive the message about subscribed topic from IoT Core



⑦ If you publish the message through the test function in AWS IoT Core to the subscribe topic, you can see that the W5100S-EVB-Pico receive the message about the subscribe topic.

| aws Services 🔻 | | Q Search for services, features, marketplace products, and docs [Alt+S] | 🖨 Giung Kim 🔻 Seoul 🔻 Support 🔻 |
|--------------------------------------------------|--------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------|
| AWS IoT $\qquad \times$ | AWS IOT > MQTT test client | | |
| Monitor | MQTT test client Info | | |
| Activity | Management of the MOTT have all and the | onitor the MQTT messages being passed in your AWS account. Devices publish MQTT messages that are identified by topics to communicate th | |
| ▶ Connect | | ontor the MQTT messages being passed in your AWS account. Devices publish MQTT messages that are identified by topics to communicate the and events. You can subscribe to MQTT message topics and publish MQTT messages to topics by using the MQTT test client. | neir state to AWS Io1. AWS Io1 also publishes MQ11 messages |
| ▶ Manage | | | |
| ▶ Fleet Hub | Subscribe to a topic P | ublish to a topic | |
| Greengrass | Topic name The topic name identifies the message. T | he message payload will be published to this topic with a Quality of Service (QoS) of 0. | |
| Secure | Q, \$aws/things/my_rp2040_thin | g/shadow/update/accepted X | |
| ▶ Defend | Message payload | | |
| ▶ Act | { "message": "Hello from AWS IoT | ronsole" | |
| Test |) | | |
| | Additional configuration | | |
| Software | Publish | | |
| Settings Learn | | | |
| Feature spotlight | Subscriptions | Торіс | |
| Documentation 🛽 | Subscriptions | τορις | |
| New console experience Tell us what you think | You have no topic subscriptions. | Subscribe or select a topic to view incoming messages. | |
| | | | |
| | | | |
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Figure 25. Publish the message from IoT Core



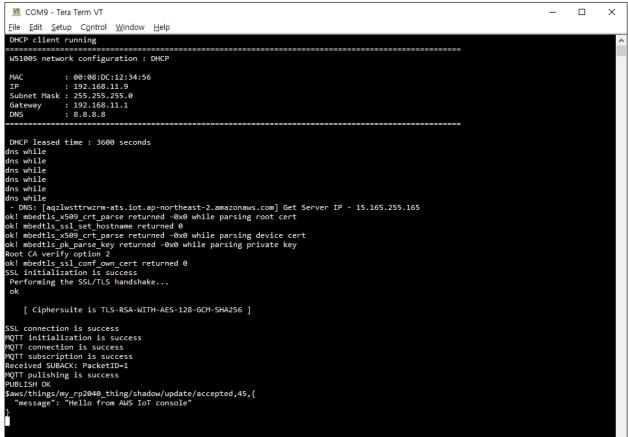


Figure 26. Receive the message about subscribed topic from W5100S-EVB-Pico

11 Debugging

① Connect to the serial COM port of W5100S-EVB-Pico with Tera Term to view logs and debugging.



| VT | Tera Term | - [di | sconnecte | ed] VT | | | | | | | _ | \times |
|------|-----------|-------|-----------|--------|------|-------------------|----------------------|-----------------------------------------------------------|--------------------------------------------------------|----------------------------------------------------|---|----------|
| File | Edit Set | up | Control | Window | Help | | | | | | | |
| | | | | | | Tera Term: New co | nnection | | | × | | ^ |
| | | | | | | O TCP/ <u>I</u> P | Service: | myhost.exam Hist <u>o</u> ry Telnet SSH Other | TCP port#: 22 SSH version: SSH2 IP version: AUTO | | | |
| | | | | | | Sgrial | Po <u>r</u> t: OK | COM9: USB Cancel | 직렬 장치(COM9) <u>H</u> elp | | | |
| | | | | | | | | | | | | ~ |

Figure 27. Connect to the serial COM port of W5100S-EVB-Pico

- ② When connecting to the serial COM port of W5100S-EVB-Pico, use following settings to set up the serial port.
 - Baud rate : 115,200
 - Data bit : 8
 - Parity bit : none
 - Stop bit : 1
 - Flow control : none



| 🔟 COM9 - Tera Term VT | | _ | \Box \times |
|-----------------------------------------------------------------------------------------------------------------|------------------------------------------------------|---|-----------------|
| ile Edit Setup Control Window Help | | _ | |
| Tera Term: Serial po | t setup and connection | × | ^ |
| <u>P</u> ort: Sp <u>e</u> ed: | COM9 ∨ 115200 ∨ | | |
| Data: | 8 bit ~ Cancel | | |
| P <u>a</u> rity: | none ~ | | |
| <u>S</u> top bits: | 1 bit ~ <u>H</u> elp | | |
| Elow control: | none ~ | | |
| Trans | nit delay msec/ <u>c</u> har 0 msec/ <u>l</u> ine | | |
| Device Friendly Device Instance Device Manufac Provider Name: Driver Date: 6-2 Driver Version: 1 | Vicrosoft I-2006 | | |
| < | × | | |
| | | | |
| | | | ~ |

Figure 28. Set up serial port

③ If everything works normally, you can see the W5100S-EVB-Pico's network information, publishing the message at intervals of 10 seconds and receiving the message about the subscribe topic through logs.



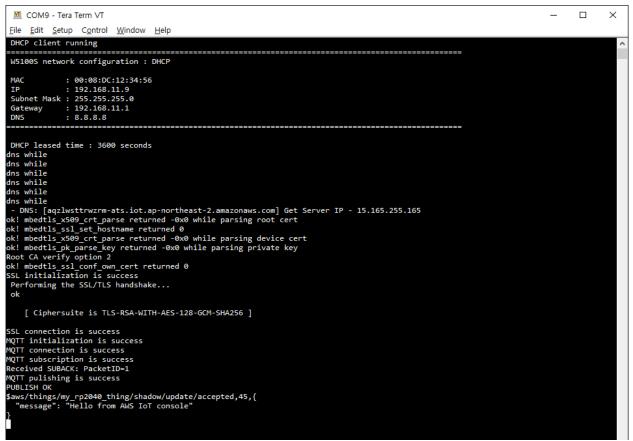


Figure 29. works normally

④ If there occurs any problem, the error log is printed showing function what the problem has occurred.



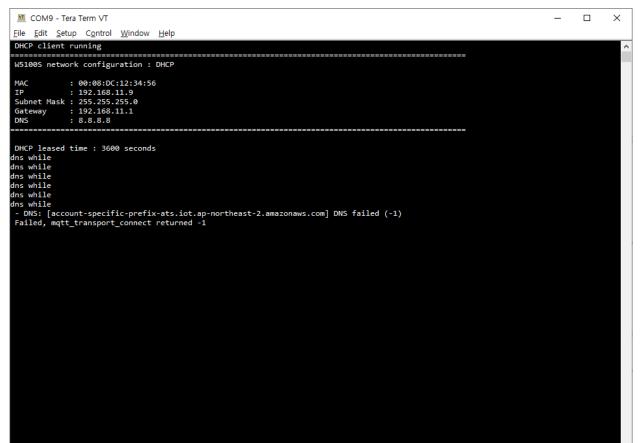


Figure 30. Failed in DNS

12 Troubleshooting

If you have any questions or problems while using the W5100S-EVB-Pico examples, please leave them at the link below.

- WIZnet Developer Forum
- <u>RP2040-HAT-C Issues</u>
- <u>RP2040-HAT-AWS-C Issues</u>